

# VAL NEMO

# **Next Generation Meta Operating System**

# D2.3 Enhancing NEMO Underlying **Technolog**





#### **Keywords:**

Cybersecure Micro-services' Digital Twins, Cybersecure Federated Deep Reinforcement Learning, Federated Machine Learning, federated meta Network Cluster Controller, Time Sensitive Networking

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PENDING EC APPROJAL





# Executive Summary

The main goal for this document is to outline the work conducted in the three tasks of WP2, emphasizing the components that form the underlay layer of the meta-OS of NEMO (i.e., three components plus the TSN capabilities). In here it is provided a thorough description, focusing on overcoming the initial challenges related to the development of these components as they begin to coexist within the same ecosystem. Through this discussion, the reader will gain a clear understanding of the advancements proposed by NEMO partners relative to the deployment and advances for the technologies utilized.

The document highlights the achievements made thus far during the Enhance phase, with particular attention to the overall deployments and internal integrations employed to develop and report the Proof of Concepts (PoC) for each of the main subcomponent. This phase finalizes with three of the four components (CMDT, mNCC and TSN) in an integration stage, with some functional and non-functional improvements from the previous version, and with the final stable version of the CF-DRL.

To completely understand this work it is important to have had a previous reading of the *D2.2 Enhancing NEMO Underlying Technology* [1] as this document, due to the fact that is an extension of it and it works as a continuation for the initial integration done in the previous phase.

Once finalized, the reader should end with a big-picture knowledge of the four main components depicted in here, being able to understand the motivation and functionality of each of these components and have a clear view about what to expect for the final developing phase.

The main results for this document included:

- A final approach to a stable version for the Cybersecure Micro-Services Digital Twin, with an overlook about how it is deployed and how it works.
- A final stable version of the Cybersecure Federated Deep Reinforcement Learning with a comprehension of the internal architecture and a description of each of the algorithms available to be run in the first stable version.
- A final approach to a stable version for the Federated meta-Network Cluster Controller, with an initial deployment of the service provisioning and the network monitoring and exposure capabilities.
- A final approach to a stable version of the Time Sensitive Network component for 5G networks.

As conclusion, this document depicts the main advances in the deployment of the NEMO technological enables, providing a deep understanding of how each of them works and the updated contributions already done in a concluded development and deployment phase. During the elaboration of this document some initial approaches proposed in the previous stage have been enhanced and some others have been dropped as there were considered as unnecessary or redundant. Also, the presence of external difficulties has made CMDT and mNCC suffer changes to adapt to the new consortium status, impacting these difficulties in the completeness of these components but not in a critical way.

In the current phase, it is expected to develop the final deployment and validation for each of the four components, and an improvement on the integration inside the full NEMO meta-OS ecosystem.





# 1 Introduction

### 1.1 Purpose of the document

This document works as an update from *D2.2 Enhancing NEMO Underlaying Technology* [1] ,providing an updated view of each of the three components defined in WP2. The main goal is to describe the latest version of each component and its parts, providing a complete knowledge about each of them and how is the final stable version. Additionally, it is also depicted how these components interact with other NEMO components, focusing on the functionalities provided and the interfaces exposed, being this crucial for the overall NEMO stack integration steps. Moreover, the document will serve to evaluate the latest status of the components against the NEMO KPIs. The three components described (each of them carried out in one of the Task withing the Work Package) are going to focus on topics as cloud and edge computing, networking, AI operations, and microservices-oriented architectures, being important to have a background on these technologies.

### 1.2 Relation to other project work

*D2.3 Enhancing NEMO Underlaying Technology* works as an update to *D2.2 Enhancing NEMO Underlaying Technology*, providing advancements on the technologies defined in there and giving the latest view of its implementation. D2.3 will follow the same structure and objectives as D3.2 and D4.2 providing a jointed view of NEMO architecture and implementation and working as a description of the integration work and the evaluation of Use Cases described in D5.2 NEMO Living Labs use cases evaluation results at Milestones 8 and 11.

### 1.3 Structure of the document

This document starts with an introduction and explanation of the context and goals defined to be addressed here. Then, there will be a section for each of the three WP2 components, and a last one for the Time Sensitive Networking, due to its characteristics. In each of these sections dedicated to the components it is provided an overview of what is being pursued in each of them, the final improved architecture, how each of these components works and the interfaces to communicate with the rest of NEMO components.

Once components are depicted in the theoretical way, there is also a section 6 for the explanation and validation of each of them, showing proofs of concept that evaluate the functionalities and bring a view on how the integration with the rest of NEMO WP2 architecture it's done. For the pending integrations with the rest of the NEMO components, proper descriptions and reporting will be included in the ongoing D4.3.

Finally, all the information expressed in sections 2 to 6 will be summarized in the Conclusions section, focusing on the results obtained related to the goals and challenges expected for the technologies depicted. Also, as this is the final document for the work package, this conclusion section will provide a big picture about the work realized and the benefits that these technologies bring not only to the rest of the NEMO architecture, also to the general State-of-the-Art.





# 2 Cybersecure Micro-services Digital Twins (CMDT)

# 2.1 Overview

The Deliverable D2.2 [1] describes all potential expected functionalities of the Cybersecure Microservices Digital Twins (CMDT) component, which plays a pivotal role in monitoring and assessing the status and availability of each workload defined as a Digital Twin (DT). This service is responsible for aggregating data from all available clusters, organizing and enriching it with crucial metadata—such as service ownership details—and providing consolidated, actionable insights to other services.

The role and functionalities of the CMDT have improved the previous CMDT version presented in D2.2. The main changes are in the distinction of the components' goal inside the NEMO MetaOS framework, removing unnecessary functionalities and clarifying the integration interfaces of the tool. With these changes, CMDT became near real-time data fusion and distribution service, capturing and DT life-cycle anomalies and passing them to the user interface. This means that the CMDT dashboards will remain, but will be used only for NEMO super-users, while the DT information, crucial for the end user is integrated in the NEMO LCM UI.

Additionally, the CMDT integration is finally detailed, including the definition of course of the data that is passed over the AMPQ message bus (e.g., RabbitMQ). This information is crucial to transmit the status from the distributed NEMO environment to the LCM UI in a near real-time manner. The messages include the following data:

- **Timestamp:** Depicts the exact time when the data was prepared and message sent, ensuring chronological order.
- **Workload ID**: Represents a unique identifier for the workload (e.g. Digital Twin).
- **UserID**: Represents a unique identifier for the user.
- **LinkerD retrieved info** such as network traffic to/from pod, traffic rate, and response stats.
- **Kube-state-metrics info** such as memory, and CPU utilization,
- Number of replicas: Represents a current number of replica instances (k8s pods) running for a workload. It indicates the number of instances or replica instances.
- **Status**: Describes the current and past state of the workload or k8s pods, which can be:
	- o Running



The message details currently cover all KPIs defined in section 2.2 of previous deliverable "*D2.2 Enhancing NEMO Underlying Technology*". The list of message data attributes is not fixed and could be updated in the future due to the stakeholder requests for better user experience. In the following subsections we point out the specific changes made on CMDT architecture in the last development and integration period.

### 2.2 Architecture and Approach

The initial iteration of the CMDT implementation was ambitious, incorporating numerous data sources– some of which were redundant–to gather as much information as possible and gain a comprehensive understanding of the system and its Digital Twin deployments. Following the initial deployment, we evaluated the collected data and compared the CMDT's capabilities with other NEMO services. This led us to reshape the architecture to better align with the NEMO meta-OS framework, ensuring it complemented the functionality of other services effectively.





The new version of CMDT still provides a comprehensive approach for in detail management of DT, however, the architecture is restructured in a way to guarantee seamless and real-time provision of DT status to the LCM graphical user interface (LCM UI), organized by each workload or user. In essence, this version still includes the same core functionality, without the parts as Grafana and Prometheus, which were used only to showcase the CMDT results in the past. In this final version of CMDT, which is fully integrated into the NEMO operating system, the interfaces mentioned became redundant and were removed from the core CMDT architecture.

The revised CMDT architecture is presented in Figure 1. The core services consist of **k8s Agent aggregation engine, Service Mesh Network Aggregation Engine, CMDT data fusion and broker.**  Mentioned services and their processes streamline the DT status message delivery from the infrastructure and software layer to the user space in LCM UI. Both aggregation engines rely on the data gathered through special agents locally collecting the data on each pod. The reader can find these agents shown on the bottom of Figure 1, where each cluster is monitored by Service mesh monitoring and Pod monitor. The gathered and CMDT processed data is shared on the AMPQ service (RabbitMQ). The data is consumed by NEMO services, like the  $LCM - UI$ , which uses the data to represent and status of the Digital twin health.









The sequence diagram from Figure 2 outlines the process of CMDT near real-time notifications for the LCM-UI within a distributed infrastructure. The LCM-UI monitors the #CMDT channel via RabbitMQ to receive updates. CMDT Core Services interact with multiple clusters (Cluster 1 to Cluster N) distributed across the infrastructure, gathering network mesh and service data from pods. This DT data is processed, aligned, annotated, and relayed to RabbitMQ as cluster status updates. RabbitMQ acts as a mediator, ensuring that LCM-UI remains informed of the latest statuses from each cluster, enabling near real-time notifications and streamlined monitoring capabilities for the system.



CMDT near real-time notifications for LCM-UI

Figure 2 CMDT data collection and passing to RabbitMQ

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### 2.3 Internal and External Interfacing

CMDT uses only internal interfaces to communicate with the rest of the NEMO components. The input and output interfaces include the following information:

- **INPUT**:
	- o Internal tools:
		- LinkerD (https://linkerd.io/) API to gather internal and external network traffic stats.
		- Kube-state-metrics (https://github.com/kubernetes/kube-state-metrics) API to gather Kubernetes nodes' stats (CPU, memory, storage utilization).
		- Prometheus (https://prometheus.io/) API to access internal storage to query retrospective stats.
		- Kubernetes API to gather services' and pods' state and logs.
	- o Intent-based API to access mapping between pods and workload UUID.
	- o User/workload relations.
- **OUTPUT**:
	- o **AMPQ messages**: RabbitMQ periodic and event-driven (on events/changes) messages to be consumed by other services, such as LCM and CF-DRL.
	- o **Optional GUI dashboard for NEMO**.













### 2.4 Conclusion

The CMDT has significantly changed in the last development period. The key improvement was the definition of the essential content gathered and annotated by CMDT and the most efficient and useful integration point through AMPQ.

Current simulations show that the LCM-UI will be able to gain responsiveness and near real-time digital twin visualization by using the CMDT notifications. For advanced NEMO administration users, the CMDT will still maintain the backdoor access for easier status debugging.





# 3 Cybersecure Federated Deep Reinforcement Learning (CF-DRL)

### 3.1 Overview

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One of the main applications of CF-DRL within NEMO is to help orchestrate microservices in the Meta-Orchestrator as described in D2.2

### 3.2 Architecture and Approach

#### 3.2.1 CFDRL and Meta Orchestration

- **Designing a Deep Q-Network (DQN) Algorithm**. Because the Thales library for reinforcement learning is closed source, it was not possible to share the library as is on the One lab cluster. However, it has been recoded the specific DQN algorithm for the CFDRL-NEMO application.
- **Connection to PPEF**: The PPEF can provide information about the status of the workload that concern the workload's intents' expectations set by the NEMO user. CFDRL needs to query the intent-based API automatically using a Keycloack identifier. The CFDRL queries the API at *intent-api.nemo.onelab.eu/api*. Then the information is retrieved and filtered in order to extract the relevant information. In the case of the PPEF, the relevant information<sup>1</sup> is the usage of CPU and RAM and whether it exceeds the limits set for a normal execution.



Figure 5 Result of querying the API (filtering RAM and CPU usage of the workload of interest)

 $1$  The information from the PPEF is not only limited to the CPU and RAM, but intents also include other details such as compute expectations (CPU, RAM), energy expectations, security, etc.





It's possible to follow over time the variations of the values of the CPU usage and RAM usage with respect to the maximum target values in the following figures. One thing to notice is that the usage values in blue here do not go over the limit target value in orange.



**Connection with the MO**: The connection with the meta-orchestrator is through RabbitMC On the CFDRL side the connection is made in python using the pika library. A queue was set in the RabbitMQ so that CFDRL can query it for general info about static cluster resource/specification information (such as its CPU, RAM, storage, etc), as illustrated in Figure 6 below. CFDRL obtains information about the cluster id, capacity such as CPU and memory.

| <b>NAME</b><br><b>RESTARTS</b><br>AGE<br><b>STATUS</b><br><b>READY</b>   |
|--|
| cfdrl-rabbit-deployment9-8677686865-tixdb 1/1<br>Running 8<br>68d  |
| (base) victor@capucin:-S kubectl logs cfdrl-rabbit-deployment9-8677686865-tixdb  |
| hello bitcoonec to rab   |
| Starting Consuming   |
| received new message b'{"response":[{"name":"k3s-cluster","uid":"1a058930-8dd4-4986-80c4-04c6f9831cbb","creationTimestamp":"2024-10-03T15:11:382","hubAcceptsClient":true,"capacity":{"cpu":"12","ephemeral- |
| storage":"2029975572Ki","memory":"23983932Ki","pods":"330"},"allocatable":{"cpu":"12","ephemeral-storage":"1974760234894","memory":"23983932Ki","pods":"330"},"verston":"v1.30.5+k3s1"},{"name":"rasptest"," |
| uid":"26ab1655-f353-4874-9c02-7c4ddd694dda","creationTimestamp":"2024-09-16T08:08103Z","hubAcceptsClient":true."capacity":{"cpu":"4"."ephemeral-storage":"29485028Ki"."memory":"4143584Ki"."pods":"110"}."al |
| 'locatable":{"cpu":"4"."ephemeral-storage":"28683035216"."memorv":"4143584Ki"."pods":"110"}."version":"v1.30.4+k3s1"}}."status":"ok"}'   |
| received new nessage b'{"response":[{"name":"k3s-cluster","uid":"1a058930-8dd4-4986-80c4-04c6f9831cbb","creationTimestamp":"2024-10-03T15:11:382","hubAcceptsClient":true,"capacity":{"cpu":"12","ephemeral- |
| storage":"2029975572Ki","nemory":"23983932Ki","pods":"330"},"allocatable":{"cpu":"12","ephemeral-storage":"1974760234894","memory":"23983932Ki","pods":"330"},"version":"v1.30.5+k3s1"},{"name":"rasptest"," |
| uid":"26ab1655-f353-4874-9c02-7c4ddd694dda","creationTimestamp":"2024-09-16T08:08:03Z","hubAcceptsClient":true,"capacity :("cou":"4","ephemeral-storage":"2948502BKi","memory":"4143584Ki","pods":"110"},"al |
| locatable":{"cpu":"4","ephemeral-storage":"28683035216","memory":"4143584Ki","pods":"110"},"version":"v1.30.4+k3s1"}],"status":"ok"}'  |
| received new message b'{"response":[{"name":"k3s-cluster","uid":"1a058930-8dd4-4986-80c4-04c6f9831cbb","creationTimestamp":"2024-10-03T15:11:38Z","hubAcceptsClient":true,"capacity":{"cpu":"12","ephemeral- |
| storage":"2029975572Kl","memory":"23983932Kl","pods":"330"},"allocatable":{"cpu":"12","ephemeral-storage":"1974760234894","memory":"23983932Kl","pods":"330"},"version":"v1.30.5+k3s1"},{"name":"rasptest"," |
| uid":"26ab1655-f353-4874-9c02-7c4ddd694dda","creationTimestamp":"2024-09-16T08:08:03Z","hubAcceptsClient":true,"capacity":{"cpu":"4","ephemeral-storage":"29485028Ki","memory":"4143584Ki","pods":"110"},"al |
| locatable":{"cpu":"4","ephemeral-storage":"28683035216","memory":"4143584Ki","pods":"110"},"version":"v1.30.4+k3s1"}],"status":"ok"}'  |
|  |

Figure 6 Retrieving the information from the Meta orchestrator through Rabbit MQ

### 3.3 Conclusion

ANT

The CFDRL was uploaded to the Onelab cluster and connected to the Meta Orchestrator and the PPEF so that the RL model could learn from interacting with the monitoring data.





# 4 Federated meta-Network Cluster Controller (mNCC)

### 4.1 Overview

The mNCC module is tasked with managing network connectivity and the assessment and exportation of network characteristics within the NEMO system. It serves as an intermediary between NEMO and the underlying physical network topology, providing connectivity and abstracting network services from the deployment specifics. The mNCC enables real-time access to network characteristics, allowing services to autonomously update their network perspective.

Recent updates to the mNCC have significantly enhanced its capabilities and integration within the NEMO ecosystem. The first stable version has been successfully integrated, marking a major milestone in the module's development. The intent-based library has been expanded with additional service libraries, broadening the range of network functionalities that can be expressed through high-level intents. Furthermore, the integration of expected technology adaptors has been completed, enabling the mNCC to interface with a wider array of network technologies seamlessly.

Moreover, the integration of the metric reporting and exposure capabilities has been completed, allowing for more comprehensive network monitoring and analysis. This update enables the mNCC to provide more accurate and detailed network characteristics to other NEMO components. The achievement of automated deployment, supported by the MO and the CI/CD frameworks in NEMO, represents a significant step forward in operational efficiency, streamlining the process of implementing and scaling the mNCC across various network environments.

The interaction of the different modules of the component is represented in Figure 7.

| SERVICE PROVISIONING | RabbitMQ<br>Service Req (SLOs, EP) | Intent-Based<br>System | Technological<br>Adaptors<br>Service Reg (Controler, SLOs, EP)<br>OK | <b>mNCC</b> | NeMeX<br>Network Connectivity (SLOs, EP)<br>OK                      | White Shark                                  | Compute & Net<br>technologies |
|----------------------|------------------------------------|------------------------|--|-------------|---|--|-------------------------------|
| HEALING              | Service Medification (SLOs, EP)    |                        | Serv Modification (Conn, SLOs)<br>OK                                 |             | Update Connection (SLOs, EP)<br>OK                                  |  |                               |
| INFORMATION EXPOSURE |                                    |                        | Update Network Status ()   |             | Network Status<br>Monitoring Compute Status (VIM)<br>Compute Status | Network Probing(Lat, BW, )<br>Network Status |                               |

Figure 7 Retrieving the information from the Meta orchestrator through Rabbit MQ





### 4.2 Architecture and Approach

In this section, are described the components of the mNCC. These include the Intent-Based System (IBS), which translates network requests into specific technology implementations, and the Network Metrics Exposure (NeMeX), which integrates and exports network topology and performance metrics. The mNCC also incorporates Technology Adaptors, such as the 5G Adapter and Teraflow SDN Controller, which manage specific network technologies. The Connectivity Controller, based on L2SM technology, provides secure link-layer connectivity between microservices within Kubernetes clusters.

#### 4.2.1 Intent-Based System

#### 4.2.1.1 Introduction

The Intent Based System (IBS) is a translator between different technologies, abstracting the specific details of network components from the general directives of higher-level components. This abstract order is known as Intent (an intention). It expresses an expectation of what the underlying technologies should do without knowing "the how". This concept adapts nicely with the paradigm of the mNCC to be able to scale with new Network Adaptors. Just with the addition of a new intent library, the IBS can translate an intention to a new network technology.

In the following section, there is a general overview of recent updates and the current status of the software. Additionally, how the Meta-Orchestrator (MO) utilizes intents to request different types of networks and the work in progress of the integration will be explored. This insight into the system's evolution and functionality will demonstrate how the Intent Based System continues to enhance network management and orchestration capabilities.

#### 4.2.1.2 Intent structure

In this section, the different targets, context and expectations that will trigger the different network adaptors in the mNCC will be described. Notice that the intent structure has not received any update from the version reported in [D2.2], the structure defined the 3GPP specification [3gpp 28.321]. For the sake of simplicity, not all the objects will be described. Also, the targets, contexts and expectations will be divided in tables, although the intent requests must have the complete structure defined in the Gitlab repository<sup>2</sup>.



#### Table 1: objectContext for 5G adapter

<sup>&</sup>lt;sup>2</sup>Gitlab: https://gitlab.eclipse.org/eclipse-research-labs/nemo-project/nemo-infrastructure-management/federatedmeta-network-cluster-controller/intent-based-system

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#### Table 2: expectationTarget for 5G adapter

#### Table 3: targetContext for 5G adapter



# Table 4: expectationContext for 5G adapte



### Table 5: intentContext for all adapters



#### Table 6: objecttContext for L2SM adapter









#### Table 7: objrctContext for L2SM adapter

#### Table 8: expectationContext for L2SM adapter



The complete set of possible intents and examples continue in the annexes 9.1 and 9.2.

#### 4.2.1.3 Intent lifecycle

The intent lifecycle starts with the request of the Meta-Orchestrator via the RabbitMQ queue. Once the IBS consumes the intent, it starts the classification phase. In this phase, the classifier module of the IBS compares the key attributes of the intent and matches them with one of the Intent libraries installed [D2.2]. The classification has been updated with a better subdivision of incoming intents into subintents. Also, the IBS can process several intents in the same file separated with the usual "yaml" separator "---". This enables in the MO more flexibility and scalability in the requests. In the current version, the IBS can classify an intent in the cloud continuum library and then sub divide this intent to be processed by one of the libraries capable of translating the intent into the specific technological network adaptor.



#### Figure 8 Intent workflow schema

Then, once the intent is translated by the corresponding library, the order is sent to the corresponding executioners. As they are programmed to be interfaces towards the different technologies, if the interfaces are the same, the executioners can be reused, giving the IBS flexibility and independence between the different steps in the lifecycle.





#### 4.2.1.4 Intent model in NEMO cloud continuum paradigm

The implementation of the Intent Based System (IBS) as a micro-kernel architecture significantly enhances the development and integration of new network adaptors. This modular design separates core functionality from specific network adaptor implementations, allowing for seamless integration of new technologies without modifying the central IBS components. As new network technologies emerge, corresponding adaptors can be developed and plugged into the system with minimal disruption to existing operations, ensuring scalability and future proofing. The micro-kernel approach also simplifies maintenance and updates of individual components, including network adaptors. Furthermore, it offers organizations the flexibility to develop or modify network adaptors to suit their specific needs without altering the core IBS functionality. This architectural choice ultimately ensures that the IBS remains highly adaptable, capable of evolving alongside the rapidly changing landscape of network technologies in the cloud continuum paradigm.

#### 4.2.2 Network Metrics Exposure

As defined in previous deliverables, the **Network Metrics Exposure (NeMeX)** is the component serving as the North-Bound Interface (NBI) for **mNCC**. It interacts with the internal subcomponents of mNCC and the RabbitMQ queue to export network topology and performance metrics for the managed technological domains.

NeMeX has two main functions:

- 1. **Topology view integration**: it gathers information from multiple sources and combines it into a unified, coherent topology view.
- 2. **Data modeling and performance metrics delivery**: it uses RabbitMQ to share information with other NEMO components, ensuring scalability and interoperability for the integration of technological controllers or add-ons in a standardized manner.

In its initial deployment, NeMeX establishes a connection with NEMO's RabbitMQ broker. While this version is manually configured, future versions aim to automate this process to enhance scalability, availability, and robustness. Once connected, NeMeX maps multi-domain resources to create an integrated view that combines performance values with domain-specific resources.

The process transforms three initial views into a unified topology by assigning common identifiers to the same nodes. Every *D* seconds, updated values are sent to the designated RabbitMQ queue if changes occur.

#### 4.2.2.1 Technological dependencies and requisites

The NeMeX sub-component is based on the next technologies:

- **Python3**<sup>3</sup>. This is the programming language used for almost all code in this component. Python 3 is a high-level interpreted language designed to facilitate code usability, thereby enhancing the potential for code improvements and extensions. Currently version Python3.12 is used.
- **Kubernetes (K8S)**<sup>4</sup> . is used for managing distributed systems, specifically for monitoring computational capacities required for virtualizing network resources. This choice is based on the strong presence of Kubernetes in current systems and its compatibility with other

<sup>4</sup> Official K8S documentation: https://kubernetes.io/docs/home/

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<sup>3</sup> Python3 official release: https://www.python.org/download/releases/3.0/



components of the NEMO meta-OS, from Kubernetes API we extract Node information and launch the sub-component. Currently version 1.31 is used.

Internally with NEMO, there are also some dependencies:

- **Underlay Network Probes**. NeMeX requires the deployment of the Underlay Network Probes to obtain the metrics extracted from the network. If probes are not deployed or are failing, there would be no content to expose. This would not cause a crash in the system, but the behavior would not be the expected one for the main workflow.
- **RabbitMQ**. Like what happens with the Underlay Network Probes, if there is no broker to exchange the metrics, NeMeX will be unable to push them, and therefore the behavior will not be the desired one. Also, it would neither kill NeMeX, just stopping the exposition service.

Also, there are some Python libraries also used and needed in this deployment. Although there is no need for a specific version in each of those technologies, it may be interesting to mention them just in case new implementations of those technologies include incompatibilities:

requests~=2.25 pika~=1.0 kubernetes~=31.0

About the System dependencies, all code has been tested and executed in Linux (Ubuntu 22.04 LTS) but, as the code is deployed using Kubernetes and Python3 (an interpreted language) there is no special dependency on the system to be used. Also, there are neither dependencies with hardware capabilities.

Finally, there are also configuration dependencies. These dependencies are related to the arguments to be provided during the deployment of the components

- **delay**: Time between updates (default: 3600)
- **e** cluster: Cluster id (default: 'cluster-1')
- **rmq** ip: IP where the RabbitMQ broker is available (default: '132.227.122.23')
- **rmq\_port**: Port where the RabbitMQ broker is available (default: '30403')
- **exchange**: Exchange used int the Rabbit MQ (default: ' ')
- **key**: Key used in RabbitMQ (default: 'costs-map')
- **user**: Nemo user for pushing RabbitMQ messages (default: 'nemo-user')
- **passwd**: Password to push RabbitMQ messages (default: '1234')

These arguments should be passed using the Kubernetes manifest available in the NeMeX official repository<sup>5</sup>.

#### 4.2.2.2 Internal workflow

When the NeMeX execution starts, this subcomponent evaluates if it has any topology stored locally (for example, in case tests are performed and the function in charge of reading the metrics is launched more than once without deleting the local data). In case there is no topology already stored, one will be loaded natively. Initially this topology was enhanced through a graph management, to provide path

<sup>&</sup>lt;sup>5</sup> kubefiles/02\_nemex-deployment.yaml · main · Eclipse Research Labs / NEMO Project / NEMO Infrastructure Management / Federated Meta-Network Cluster Controller / Network Exposure module · GitLab

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Computation capabilities, but due to the lack of demand for this service, we have proceeded to use local dictionaries, which consume a smaller amount of memory and have a faster management.

Once the topology update is initialized, two data sources will be evaluated: Kubernetes to obtain the mapping between the Kubernetes nodes and the IPs that represent them and the *Underlay Network Probes*. From the *Kubernetes API (client.CoreV1Api())* the node information is loaded, extracting the name and IP values from the *metadata.name* and *status.addresses* field.

Afterwards, and having these measurements, the different metrics repositories of the *Underlay Network Probes*, which are present in each node of the cluster through a Prometheus service on port 5001, are analyzed. For each node, the metrics and properties are read and parsed into the format defined for the output. If any node does not have the service available or does not provide these metrics, the error will be detected, and it will be discarded from the process.

Once we have all the metrics processed, they are integrated in the same JSON, including the timestamp of when they have been generated and the cluster from which they come, to allow the identification of these. This resulting JSON is sent to the **RabbitMQ** broker indicated in the deployment and the process is paused until the next iteration. This process is depicted in Figure 9.<br>
PENDING K.C. AP







Figure 9 NeMeX internal workflow.





#### 4.2.2.3 Deployment and permissions.

The NeMeX component is designed to be deployed in a Kubernetes environment, in which write permissions are not required but read permissions are required. In the deployment process there are two steps that must be performed sequentially: on the one hand the definition of the *Namespace* where they will be executed (in the case of the Nemo project this is **nemo-net**) and the *Deployment* of the NeMeX resources. Both documents are available in the eclipse repository <sup>6</sup>.

Within NeMeX resources, we have 4 necessary deployments:

- 1. **Deployment**: this is the deployment of the code. Here the image to be instantiated is identified as well as the parameters that will serve as variables. These parameters can be parameterized or hardcoded. The user and password must be managed through Kubernetes secrets, which has not been uploaded to the repository for security reasons.
- 2. **ServiceAccount**: Creates an identity in Kubernetes for the deployment to manage the necessary resources for monitoring nodes.
- 3. **ClusterRole**: Role that NeMeX will perform within Kubernetes. In this section, read permissions are requested for the pods at namespace level and for the nodes at cluster level. This component can be replaced by a *Role*, but then it will only be able to monitor the pods at namespace level and not the nodes.
- 4. **ClusterRoleBinding**: Maps the permissions requested in the *Cluster Role* with the *Service Account* created. If a *Role* is used instead of a *Cluster Role*, a *RoleBinding* should be used instead.

#### 4.2.2.4 Inputs and outputs.

We can identify two main inputs: on the one hand we have the compute information obtained using the **Kubernetes API**; this information will help to match the nodes with their IPs. This input is managed using the Python3 Kubernetes API and the value obtained is a string with IP format per each node.

On the other hand, it is also received metric information from the network probes; these metrics will be associated with nodes and links and will be summarized in the following table:



#### Table 9. NeMeX input metrics.

<sup>6</sup> https://gitlab.eclipse.org/eclipse-research-labs/nemo-project/nemo-infrastructure-management/federated-metanetwork-cluster-controller/network-exposure-module/-/tree/main/kubefiles

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These metrics are processed and formatted to be aligned with the node names and IPs used by the Kubernetes resources to be managed. This integration returns the following data model:



#### Figure 10 mNCC metrics data model.

In Section 6 there will be available an example of the deployment and exposure of metrics, showing a demo scenario with three nodes.

#### 4.2.3 Technology Connectivity Adaptors

The final working network adaptors. There are two types of connectivity adaptors: the ones part of the NEMO project, and the ones external to the project but used as a proof of concept for the versatility and flexibility of the mNCC architecture. In section 6 the demonstration for two cases will be shown.

#### 4.2.3.1 L2SM connectivity solution

Link Layer Secure Microservices (L2SM) serves as a secure connectivity solution within the mNCC, offering advanced network functionalities through an extension of the Kubernetes (K8s) API. It enables the creation, management, and deletion of virtual networks and supports the use of custom overlay networks. By taking advantage of the Software Defined Networking (SDN) capabilities, L2SM provides an API that deploys a customized data plane and enforces rules within Open Virtual Switches (OVS) as part of the overlay network topology.

L2SM has undergone significant advancements to align with the mNCC's evolving requirements. Initially, as presented in D2.2, L2SM handled internal cluster connectivity via overlays and introduced the concept of Network Edge Devices (NEDs) to enable the interconnection of overlay networks across different clusters. This concept has been further developed and implemented, facilitating communication between workloads deployed through NEMO OS using a standardized interface.

#### **L2SM MD**

The creation and management of L2SM resources are now handled via the L2SM multi-Domain (L2SM MD) client—a gRPC server that processes requests to create inter-cluster overlay topologies, add or delete clusters, and manage inter-cluster virtual networks atop these overlays. This modular approach simplifies the expansion of L2SM's functionalities, integrating existing concepts of virtual networks and overlay networks with the new NEDs and inter-cluster networking capabilities through a standardized API. This enhances the efficiency of the mNCC's connectivity adaptor.





Specifically, L2SM MD implements the following methods:

- Create and Delete Networks: Allows the creation and deletion of virtual networks across clusters, given a list of clusters and the name of the network.
- **Create and Delete Overlays:** Manages overlay network topologies that define the interconnection of clusters, provided with a list of clusters and a name for the overlay.
- **Add and Remove Clusters:** Enables dynamic addition or removal of clusters within an overlay network, specified by the overlay name and the cluster to modify.

To securely manage these operations, L2SM MD requires cluster information, including the K8s API endpoint and a user's bearer token with permissions to manage L2SM Custom Resource Definitions (CRDs), Overlays, NEDs, and L2Networks in the managed clusters. Since the K8s API endpoint uses HTTPS, L2SM MD needs access to the TLS certificate to establish secure communication. Therefore, copies of the public certificates are stored securely within the control plane cluster as Kubernetes secrets.

To facilitate the setup of the gRPC server and ease the management of certificates and resources, L2SM MD provides a Command Line Interface (CLI) with a set of tools:

- **Apply-cert:** Takes a .key file and a cluster name as input, containing the public certificate, and stores it as a secret, allowing L2SM MD to access it securely.
- **Generate-cr:** Automates the generation of CRs by receiving input values for each resource. For example, when creating an Overlay, you input the names of clusters and links, and it generates the complete CR, including the necessary NED CRs required when connecting multiple clusters. This CLI tool mirrors the utility of the gRPC server but without actually creating the resources, serving as an alternative for quick fixes in case of errors in the workflow or for testing the adaptor in a resource-constrained environment.

#### 4.2.3.2 5G adapter: functions, capabilities and workflow update

The 5G adapter is responsible for managing data flows and providing monitoring and analytics capabilities within the 5G network. Here are its key functions with an extended definition in D2.2:



Moreover, the deployment and request of 5G network flows has been updated to achieve an automated deployment by the meta-orchestrator and the following API exposure towards the IBS. In such a way





that, the MO can request a new network flow using the unified interface provided by the IBS. This workflow is not fully implemented at the date of this deliverable since MO tasks is part of WP3 and ends later in time. The general workflow is depicted on Figure 11.



Figure 11 Towards integration workflow 5G adapter

In the Figure 11 there are shown three main phases internal interactions the network adapter:

- Deployment phase: is the one orchestrated by the MO, in charge of the deployment of the 5G core components such as the UPF, AMF, SMF...
- Optional phase: This phase has been theoretically described, as there is the possibility of connecting the different components of the core if deployed in different clusters through the L2SM adapter. From the L2SM perspective, this could be treated as a common service being connected through a L2SM network.
- Flow request phase. Once the adapter is deployed, the MO can start requesting new 5G flows through the intent-based interface connected to the RabbitMQ queue specific for the mNCC.

#### IETF TeraFlow SDN-based connectivity adapter. (External)

The ETSI TeraFlowSDN7 is an innovative, open-source, cloud-native Software-Defined Networking (SDN) controller and orchestrator designed to support smart networks and services for beyond 5G (B5G) and 6G networks. Developed by the ETSI Software Development Group TeraFlowSDN, it employs a micro-services architecture, enabling seamless integration with other ETSI initiatives such as OpenSourceMANO and compliance with standards from bodies like IETF and [2].

TeraFlowSDN is characterized by its high performance, advanced SDN automation, and support for transport network slicing, multi-tenancy, and cyberthreat analysis using machine learning (ML) and deep learning (DL) components. It also incorporates features like distributed ledger technology and smart contracts for secure network management. The controller is highly scalable, allowing for rapid

<sup>7</sup> TFS controller GitLab: https://labs.etsi.org/rep/tfs/controller/-/wikis/home

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prototyping and experimentation, and it supports the management of heterogeneous network equipment, including packet optical, IP and microwave networks [3].

The latest release, TeraFlowSDN 2.1, has been used by the mNCC IBS library to create a VPN layer 2 translation. A complete example of a request and the translated version in TFS controller format is shown in Annex 7. Briefly, the following context can be used to build an intent expectation to request a layer 2 VPN.



#### Table 10: objectContext for L2VPN

#### Table 11: expextationTargets for L2VPN



# 4.2.3.4 Network Slice Controller (External)

The IETF-based Network Slice Controller (NSC) processes end-to-end network slice requests initiated by 5G customers. These requests are coordinated by the 5G end-to-end orchestrator, which configures the Radio Access Network (RAN), and Core Network elements as needed and forwards the request to the NSC for execution. The NSC subsequently collaborates with the relevant network controllers to deploy the network slice within the transport network. [4]

There are some implementations of a network slice controller following the approach of the IETF draft (e.g., in-house Telefónica development in progress, not yet fully release as open source<sup>8</sup>). In the context of the project, the main characteristics that could have an intent for a slice request has been described as followed:

<sup>8</sup> Github: Telefonica/network slice controller: Repository created for the Network Slice Controller (NSC) development









#### 4.2.3.5 Auto peering API. (External)

Auto peering, as defined in this draft [5], refers to the automated process of establishing and managing peering relationships between different Autonomous Systems (ASes). This involves using an API to exchange necessary information, such as network details, routing policies, and contact information, to facilitate the setup and maintenance of peering connections without the need for manual intervention. The goal of auto peering is to simplify and streamline the peering process, reducing the time and effort required to establish new peering relationships and ensuring more efficient and reliable interconnectivity between networks. Although literally could not be perceived as a network connectivity adaptor, it is very useful towards future adaptors that could involve BGP session to access new routes or link state parameters [6] [7].



Figure 12: Private peering interactions





There is not a workable implementation of the process but, theoretically, the intents can be described accordingly<sup>9</sup>. The intentExpectation objects to request a new peering could contain mainly the following objectContexts:



#### Table 12: objectContext for BGP session





#### 4.2.4 Network Performance Monitoring

The Network Performance Monitoring module within the mNCC provides the basic tools to evaluate real-time network conditions. This component leverages a Python-based network performance probe to measure key metrics across diverse network environments. By utilizing socket communication, it collects granular data on throughput, latency, and packet loss. These metrics are critical for ensuring efficient network operation and supporting the autonomous decision-making capabilities of other NEMO components.

The monitoring probe supports configurable parameters, allowing for fine-tuned evaluations tailored to specific network conditions or service requirements. For example, Users can define test duration, target hosts, and ports to suit their operational needs. The monitoring tool seamlessly integrates with the broader mNCC architecture, feeding network metrics directly into the meta-OS for actionable insights. Its modular design supports deployment via containerized environments, ensuring scalability and compatibility with multi-cluster scenarios. Leveraging the CI/CD framework of NEMO meta-OS, the monitoring tool is deployed and updated automatically, aligning with the intent-based management principles of the mNCC.

<sup>9</sup> In fact, from NEMO Project standardization contributions are being proposed for the definition of interconnection intents, e.g. https://datatracker.ietf.org/doc/draft-contreras-nmrg-interconnection-intents/.

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### 4.3 Conclusion

The Federated Meta-Network Cluster Controller represents a key module in the NEMO meta-operating system, bringing an innovative solution for network management for edge-cloud environments. Throughout its development, the mNCC has evolved into a robust and flexible framework designed to address the challenges of scalability, adaptability and interoperability across diverse network technologies and multi-cluster scenarios.

The technological progression of the mNCC highlights its work as an infrastructure manager that simplifies and abstracts the complexities of network management. Conceptualized to cover the gap between the NEMO meta-Orchestrator and underlying network infrastructures, the mNCC has deployed its capabilities through the integration of intent-based networking and advanced metric exposure mechanisms with a secure solution for network connectivity, that works as the main technological adaptor, having also the capability to use up to five different technological adaptors according to the needed scenario (KPI 3.3, at least 5 technological adaptors). These developments have allowed the mNCC to not only provide seamless connectivity but also enable the capability of NEMO meta-OS to make dynamic and data-driven decisions.

The mNCC's architecture is built around the principles of abstraction, interoperability, and automation, enabling it to efficiently manage and monitor network operations across diverse environments. By leveraging an intent-based system, the mNCC translates high-level service expectations into detailed network configurations, allowing services to operate with greater autonomy and reduced reliance on manual intervention. This capability significantly enhances scalability, a critical requirement in distributed and multi-cluster settings, making the deployment of 50 Network Segments in 3.531s (KPI 3.1, < 5ms). Additionally, the integration of advanced metric collection and exposure mechanisms provides real-time insights into network performance. This feature supports network optimization and facilitates seamless interoperability between the mNCC and other NEMO components, such as the Meta-Orchestrator.

Looking forward, several areas for improvement and expansion have been identified to ensure the continued relevance and effectiveness of the mNCC. One priority is the integration of advanced security features, such as Zero Trust solutions, which will strengthen the module's defense mechanisms in distributed network scenarios. Additionally, optimizing resource allocation in dynamic and resourceconstrained environments is an ongoing focus. Addressing these challenges, with the potential introduction of AI-based engines, is one of the main paths to follow during the next steps of the component.

In conclusion, the mNCC has completed the main goals expected for the component, even it is still at an early Technology Readiness Level (TRL), the proofs of concept done show a potential solution for multi-environment scenarios, allowing quick reactions and an abstraction level that reduces the complexity to integrate it with external modules, being the first step for seamless operation in nextgeneration network ecosystems.





# 5 Time Sensitive Networking

# 5.1 Overview

Time Sensitive Networking (TSN) features enable synchronizing mobile network UEs. TSN can be used to synchronize mobile network with existing IT infrastructure.

The industrial LAN may also consist of TSN-enabled Ethernet bridges. The latest release of 5G specification (Rel. 18) supports the fully centralized TSN configuration model, where a central controller should be able to configure both Ethernet and 5GS bridges as a unified network. The 5GS supports the whole industrial network, both Medium Access Control (MAC) learning and flooding based forwarding as well as the static forwarding configured by the central controller need to be supported. 3GPP has defined that a 5GS can be modelled as one or more virtual TSN bridges.

Within the context of NEMO, TSN will be a complement in the sense that the edge-cloud continuum infrastructure becomes extended with TSN domains, where the control functional entities of the 5G network, as well as other functions (e.g., content endpoints, application workloads, etc) are instantiated leveraging on NEMO infrastructure and stack.

### 5.2 Architecture and Approach

TSN implementation ensures centralized, precise time distribution to UEs for ultra-reliable, low-latency communication as shown in the Figure 13 below.



Figure 13: TSN Architecture

 CNC and TSN AF Integration: The TSN Centralized Network Controller (CNC) is responsible for configuring bridges within the TSN-enabled network, allowing time-





synchronized data transfer from the Grand Master to each UE. The TSN Application Function (AF) interfaces with the 5G control plane, translating TN parameters to 5GSspecific settings and reporting the capabilities of the 5GS bridge (e.g., delay specifications and topology details).

- 5G QoS Mapping: Ethernet and TSN traffic flows are mapped to 5G QoS flows to maintain service quality. This mapping allows the CNC to optimize flows' handling across the network, supporting per-stream filtering, traffic policing, and VLAN configuration in compliance with IEEE 802.1Q.
- Seamless Redundancy and Preemption: TSN framework offers Seamless Redundancy for ultra-reliable communication and Frame Preemption to prioritize time-critical information.
- Time Synchronization: Through the TSN Translator (DS-TT) on UEs, precise time synchronization is achieved using gPTP messages, adhering to 3GPP specifications (24.535).

### 5.3 Internal and External Interfacing

**TSN AF** is part of 5GC and provides the control plane translator functionality for the integration of the 5GS with a TSN network, e.g. the interactions with the CNC. The TSN AF interfaces towards the CNC for the PSFP (IEEE Std 802.1Q) managed objects that correspond to the PSFP functionality implemented by the DS-TT and the NW-TT. Thus, when PSFP information is provided by the CNC, the TSN AF may extract relevant parameters from the PSFP configuration. The TSN AF calculates traffic pattern parameters (such as burst arrival time with reference to the ingress port and periodicity). TSN AF also obtains the flow direction. TSN AF is responsible for forwarding these parameters in TSC Assistance Information (TSCAI) Container to the SMF (via PCF). TSN AF may enable aggregation of TSN streams if the TSN streams belong to the same traffic class, terminate in the same egress port and have the same periodicity and compatible Burst arrival time. One set of parameters and one container are calculated by the TSN AF for multiple TSN streams to enable aggregation of TSN streams to the same QoS Flow.

**NW TT** (Network TSN Translator): supports link layer connectivity discovery and reporting as defined in IEEE Std 802.1AB for discovery of Ethernet devices attached to NW-TT. When integrating normal devices, we cannot assume that would be a DS-TT does not support link layer connectivity discovery and reporting, then NW-TT performs link layer connectivity discovery and reporting as defined in IEEE Std 802.1AB for discovery of Ethernet devices attached to DS-TT on behalf of DS-TT. If NW-TT performs link layer connectivity discovery and reporting on behalf of DS-TT, it is assumed that LLDP frames are transmitted between NW-TT and UE on the QoS Flow with the default QoS rule. Alternatively, SMF can establish a dedicated QoS Flow matching on the Ethertype defined for LLDP (IEEE Std 802.1AB).

**DS-TT** (Device Side TSN translator): translate the TSN 802.1 protocols on top of 5G networks but cannot be assumed that would be a DS-TT capable UEs.

### 5.4 Conclusion

As it points out, TSN main characteristics are performed: Seamless Redundancy that permits ultrareliability due to the duplicity of buffers, Frame Pre-emption that includes a priority of the information that produces, and time critical communication. In addition to the Time Aware Shaper that allows scheduling of the outputs and Time Synchronization.





# 6 Proof of Concepts

The Proof of Concepts chapter demonstrates the practical implementation and functionality of the key components developed within the NEMO project. This section showcases the integration and performance of the Cybersecure Micro-services Digital Twins (CMDT), Cybersecure Federated Deep Reinforcement Learning (CF-DRL), and the meta-Network Cluster Controller (mNCC) in various scenarios. Through detailed demonstrations and analyses, we evaluate the components against their defined Key Performance Indicators (KPIs) and illustrate their interactions within the project ecosystem. The following subsections provide in-depth insights into each component's deployment, operational workflows, and achieved results, highlighting the advancements made from the initial versions.

### 6.1 CMDT first stable version

#### 6.1.1 Detailed description

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The easiest way of demonstrating the functionality of CMDT is to showcase it on a real example. For this reason, we took an application developed for NEMO Meta-OS, deploy it as digital twin and present the CMDT actions in live environment. For the app we selected the isolated ASM Terni deployment of PMU devices and applications that are controlling it. This will be our Digital Twin for this section. The simplified workload includes PMU devices deployed in the network, edge device for pre-processing the data locally on the site and cloud service, which is used to aggregate the data from edge devices and initiate actions towards the devices on the field. The application allows reviewing the status, gathering data and Firmware update over the air (FOTA). The digital twin of the workload comprises all mentioned device logs that can describe application footprint and behavior.

One crucial message that a user would request from the CMDT would be a list of services (Digital twin components) that represent a digital twin, and a corresponding status. A list of all workloads that CMDT can get from NEMO infrastructure is presented in Figure 14.







Figure 14: List of resources per workload.







Figure 15 The CMDT message example which is transported over RabbitMQ

The CMDT monitors the status of each workload component continuously and distributes this information accordingly. This represents workloads DT status, which is timestamped for each event and transmitted the LCM and LCM – UI service. This notification path is crucial to notify the user about the status of any component in the workload. The messages that are passed over the RabbitMQ are sent for each component on the #CMDT channel. Example of such CMDT message structure (Figure 15) includes all information that was already explained and defined in the Deliverable D2.2, e.i. rates of times in quantiles and rates of response codes, e.g. 200 for OK and 500 for Server Error. From "res rate by code" parameter (Figure 15) user can find that our demo application two requests per minute with return the content successfully (code 200) and once per 6 minutes application responded with server error (Code 500).





An additional improvement from the last version of CMDT is the introduction of the pod status block. For higher reliability and avoiding missing the information when some services are restarted, the block includes last N status changes attributed with the timestamps. As already presented in this document, the recipient of this data is LCM UI, which creates graphics and continuously updates user with the status of his digital twin workload living on NEMO infrastructure.

In this proof of concept, we presented the CMDT operation on real-world example that is deployed in NEMO. The workload status is constantly monitored, processed, collected and sent to the LCM UI. With the demonstrated example we showed the effectiveness of the CMDT service and outline the progress from the previous deliverable D2.2.

### 6.2 CF-DRL first stable version

We demonstrate the run of the CFDRL for the scaling the replicas of the workloads in the Meta-Orchestrator.



Figure 16 CFDRL communication architecture for scaling the replicas of the workloads in the Meta-Orchestrator

The first step is to deploy the CFDRL docker container to the Onelab cluster. Once the code is containerized. It is sent to the cluster using the commands:

export KUBECONFIG="/home/victor/nemo/victor.gabillon-kubeconfig.yaml" ubectl apply -f -n nemo-ai

Then the run of the CFDRL can be monitored using the kubernetes functions:



The CFDRL automatically connects to the Meta Orchestrator with RabbitMQ and with the PPEF through the intent-based API.





response = requests.get(|url: 'https://intent s=headers)  $\verb|print('response', 'response, 'type (response), 'response, status\_code)$ 

Figure 17: Code snippet for request

In the code the connection in Python to the intent-based API is made witha request to https://intentapi.nemo.onelab.eu/api/v1/intent/

The connection to the intent-based API requires an identification token (bearer token) that expires every 2 hours. A curl request periodically is sent to the NEMO Identity Management component to re-initiate the token.



The information received from the PPEF (through the intent-based API) is filtered in order to focus on the CPU and RAM of each workloads.

This allow us to display the change of the CPU and RAM though time:



Meta Orchestrator connection:

The connection with the meta-orchestrator is through RabbitMQ. On the CFDRL side the connection is made in python using the pika library.







#### Figure 18: RabbitMQ connectiviy snipped

A queue was set in the RabbitMq so that CFDRL can query it for general info about the network as illustrated in the Figure below. CFDRL obtains information about the cluster id, capacity such as CPU and memory.



# 6.3 mNCC hybrid clusters and intent networking

#### 6.3.1 Single Cluster Connectivity throughout L2SM overlay adaptor

In order to demonstrate the advances of the L2S-M connectivity adaptor in the NEMO project, this new PoC showcases the automatic setup of the adaptor in a NEMO inter-domain cluster environment in order to enable the deployment of virtualized workloads within the infrastructure of the project. Since the internal components that enabled this connectivity were previously shown in D.2.2, this new PoC will focus on showcasing the ability of the new L2S-M-MD module (described in Section 4) to properly configure new k8s clusters to the NEMO project, ensuring their ability to create inter-domain virtual networks that enable the connectivity of network functions in multiple K8s clusters.

Particularly, this setup consists of three separate K8s clusters: one controller cluster and two worker clusters, all following the guidelines of the NEMO project hierarchy and its characteristics. In this regard, for the K8s control plane cluster, the L2SM-MD-server, the IDCO provider and multidomain DNS components were installed, while the L2S-M operator and its components were installed in the L2S-M namespace of the K8s worker clusters. This setup can be seen in Figure 20: K8s clusters of this PoC.

alex@alex-pc:~/Documentos/l2sm/l2sm-md\$ kind get clusters control-plane worker-cluster-1 worker-cluster-2

Figure 20 K8s clusters of this PoC





| alex@alex-pc:~/Documentos/l2sm/l2sm-md\$ kubectl get pods -n l2sm-system --context kind-worker-cluster-1 |              |                     |                               |                 |  |
|--|--------------|---------------------|-------------------------------|-----------------|--|
| <b>NAME</b>  | <b>READY</b> | <b>STATUS</b>       | <b>RESTARTS</b>               | AGE             |  |
| l2sm-controller-79f946d5d8-zxdqk   | 1/1          | Running             | $\theta$                      | 34m             |  |
| l2sm-controller-manager-6dcc4f94d5-t65ng   | 2/2          | Running             | 2 (32m aqo)                   | 34 <sub>m</sub> |  |
| alex@alex-pc:~/Documentos/l2sm/l2sm-mdS kubectl get pods -n l2sm-system --context kind-worker-cluster-2  |              |                     |                               |                 |  |
| <b>NAME</b>  | <b>READY</b> | <b>STATUS</b>       | <b>RESTARTS</b>               | AGE             |  |
| l2sm-controller-79f946d5d8-nv2zd   | 1/1          | Running             | 0                             | 34 <sub>m</sub> |  |
| l2sm-controller-manager-6dcc4f94d5-4sg5f   | 2/2          | Running             | 2(32m aqo)                    | 34m             |  |
| alex@alex-pc:~/Documentos/l2sm/l2sm-md\$ kubectl get pods -n nemo-net --context kind-control-plane       |              |                     |                               |                 |  |
| <b>NAME</b>  | READY        | <b>STATUS</b>       | <b>RESTARTS</b><br><b>AGE</b> |                 |  |
| l2smmd-coredns-7b9cbfbc5f-9rgwg  | 2/2          | Running<br>Θ        | 13m                           |                 |  |
| l2smmd-idcoprovider-584cdbfc6d-4qnqs   | 1/1          | Running<br>$\theta$ | 26m                           |                 |  |
| $12cmnd_0$ cerver-85dc97858c-jonn $l$  | 111          | <b>Punning</b>      | 1.3 <sub>m</sub>              |                 |  |

Figure 21 Resources present in the clusters in the PoC

Since we are interested in enabling the management cluster to configure and deploy new components and K8s resources in the worker clusters, it is necessary to generate the public certificates of their respective server APIs and the tokens that enable the management for K8s resources in each cluster, which can be done using the K8s CLI as seen in Figure 22 and Figure 23.



![](_page_43_Figure_5.jpeg)

| alex@alex-pc:~/Documentos/l2sm/l2sm-mdS kubectl create token -n l2sm-system  | l2sm-controller-manager --context kind-worker-cluster-1 |  |
|--|---|--|
| eyJhbGciOiJSUzI1NiIsImtpZCI6ImlaYWxJTnR4MTktazJ3dnhmbjg50GVuM3lCd0ZkLV9UcFQtMXl0QXU4RWcifQ.eyJhdWQiOlsiaHR0cHM6Ly9rdWJlcm5ldGVzLmRlZmF1bHQuc3ZjLmNsdXN0ZXI |   |  |
| ubG9jYWwiXSwiZXhwIjoxNzM0MDEyOTqzLCJpYXOi0jE3MzOwMDkzODMsImlzcyI6Imh0dHBzOi8va3ViZXJuZXRlcy5kZWZhdWx0LnN2Yy5jbHVzdGVyLmxvY2FsIiwia3ViZXJuZXRlcy5pbyI6eyJuY |   |  |
| W1lc3BhY2UiOiJsMnNtLXN5c3RlbSIsInNlcnZpY2VhY2NvdW50Ijp7Im5hbWUiOiJsMnNtLWNvbnRyb2xsZXItbWFuYWdlciIsInVpZCI6ImJiZjY1YzllLTI3NWMtNGYyYy1iN2ZjLTY3ODYxNTJkNGI |   |  |
| 5ZiJ9fSwibmJmIjoxNzM0MDASMzqzLCJzdWIiOiJzeXN0ZW06c2VvdmljZWFjY291bnO6bDJzbS1zeXN0ZW06bDJzbS1jb250cm9sbGVvLW1hbmFnZXIifO.jqwCJ3IAOLl0sUhrljvt5OGazZYrRDYVUI |   |  |
| VyDWEDja xyEvE4kD2covkFchl6B1YtwlKcqVT8rYrdAog9-7-pTBZx45iKYy-ZepXbwFqw8wikn3dsw-B6a-2kBiJEOu-w0ZyIq2oPfRa2VI1jHJmKyEe50Tt0a930rdEAa ne6scu7K4BB 79YVsfmV  |   |  |
| cb-BA3zLksPl5PfA3PujWtRBViYo2U1lsIOfsnmfqUq0uRz0YKjTw0eIvrjvwc2lB80KP88uc9AHCwWqWvwNCDWq4Uhl-BnRV2EqAcFWVldx 7VYfP8VbzKiM1DTPHvcn5UH6T2fYEqy4KvSCKhwOXNUbw |   |  |
|  |   |  |
| evJhbGciOiJSUzI1NiIsImtpZCI6IlZxYnd6WUFFdDVBcFk0M3NZNmxqaG1veGc5b2lYeWdFTTFodHN6dWtiTUEifO.evJhdWOiOlsiaHR0cHM6Lv9rdWJlcm5ldGVzLmRlZmF1bHOuc3ZiLmNsdXN0ZXI |   |  |
| ubG9jYWwiXSwiZXhwIjoxNzM0MDEyOTg4LCJpYXOiOjE3MzOwMDkzODgsImlzcyI6Imh0dHBzOi8va3ViZXJuZXRlcy5kZWZhdWx0LnN2Yv5jbHVzdGVvLmxvY2FsIiwia3ViZXJuZXRlcv5pbvI6evJuY |   |  |
| W1lc3BhY2UiOiJsMnNtLXN5c3RlbSIsInNlcnZpY2VhY2NvdW50Ijp7Im5hbWUiOiJsMnNtLWNvbnRyb2xsZXItbWFuYWdlciIsInVpZCI6IjQ3ZDNiMzY5LWJiZDqtNGNmZS1hNDdkLWM2MzRhMjBmMjk |   |  |
| 2MSJ9fSwibmJmIjoxNzM0MDA5Mzq4LCJzdWIiOiJzeXN0ZW06c2VvdmljZWFjY291bnO6bDJzbS1zeXN0ZW06bDJzbS1jb250cm9sbGVvLW1hbmFnZXIifO.pPV xO GJVCtsfzORbDJqBzavZh1HsEIf9 |   |  |
| y0sJKZNdRtDVxsLILj 0PaNwqU61fTNqcoZAGKSGCqGv-a0oW1xedHHfJ0qYu2HspR7RBOfCK6cGBqZ6-WsMeJkJYG2f01b0hcdp7jWqDqK8J88WIKKnRtPPqX-EMAovqDKchNmd7U21-eAqTjYypZtx 5 |   |  |
| kk7f9NRjG3152qma9qPNjAFbIsICzSu9E5iOF92SGSsGQqx16LWa3mW2lYoehTKj16Yhtw8I-OVLkw6uZ4S2 9ULYp 54EV0x05H8DrgztGFvzk0k7S 8McTXCO077sRtLp94kfLmuvBl8MG5lxflBW-RA |   |  |

Figure 23 K8s cluster token generation

![](_page_43_Picture_75.jpeg)

![](_page_44_Picture_0.jpeg)

Once all the elements have been created to enable the management of the K8s resources in the clusters that are going to be managed by the mNCC component, the system administrator can proceed to create a slice (i.e., inter cluster overlay that will logically connect both clusters) between both clusters. To do so, it is necessary to introduce the API endpoints and the generated tokens to perform a gRPC call, as it can be seen in Figure 24:

![](_page_44_Figure_2.jpeg)

![](_page_44_Figure_3.jpeg)

With these values, the administrator can proceed with the creation using the available API in the manager cluster, which will install both NEDs and the overlay network (slice) in the managed K8s clusters as their own resources, as seen in Figure 25:

![](_page_44_Picture_5.jpeg)

![](_page_44_Picture_103.jpeg)

![](_page_45_Picture_0.jpeg)

| <b>NAME</b>                | AVAILABILITY                             | <b>CONNECTED PODS</b>                | AGE        | alex@alex-pc:~/Documentos/l2sm/l2sm-md\$ kubectl get l2networks --context kind-worker-cluster-1                   |  |
|----------------------------|--|--------------------------------------|------------|---|--|
| ping-network               | Available                                |                                      | <b>23s</b> |   |  |
|                            |  |                                      |            | alex@alex-pc:~/Documentos/l2sm/l2sm-md\$ kubectl get l2networks --context kind-worker-cluster-2                   |  |
| <b>NAME</b>                | AVAILABILITY                             | <b>CONNECTED PODS</b>                | <b>AGE</b> |   |  |
| ping-network Available     |  |                                      | 22s        |   |  |
|                            |  |                                      |            | alex@alex-pc:~/Documentos/l2sm/l2sm-md\$ kubectl describe l2networks ping-network --context kind-worker-cluster-2 |  |
| Name:                      | ping-network                             |                                      |            |   |  |
| Namespace:                 | default                                  |                                      |            |   |  |
| Labels:                    | $nones$                                  |                                      |            |   |  |
| Annotations: <none></none> |  |                                      |            |   |  |
|                            | API Version: l2sm.l2sm.k8s.local/v1      |                                      |            |   |  |
| Kind:                      | L2Network                                |                                      |            |   |  |
| Metadata:                  |  |                                      |            |   |  |
|                            | Creation Timestamp: 2024-12-12T13:32:28Z |                                      |            |   |  |
| Finalizers:                |  |                                      |            |   |  |
|                            | l2sm.operator.io/finalizer               |                                      |            |   |  |
| Generation:                |  |                                      |            |   |  |
|                            | Resource Version: 12305                  |                                      |            |   |  |
| UID:                       |  | 3b74dfb2-d93f-42b4-9509-c033a704443b |            |   |  |
| Spec:                      |  |                                      |            |   |  |
| Provider:                  |  |                                      |            |   |  |
|                            | Domain: 172.20.0.2:8181                  |                                      |            |   |  |
| Name:                      | test-slice                               |                                      |            |   |  |
| Type:<br>Status:           | vnet                                     |                                      |            |   |  |
|                            | Internal Connectivity: Available         |                                      |            |   |  |
|                            | Provider Connectivity: Available         |                                      |            |   |  |
| Fvents:                    | $nonez$                                  |                                      |            |   |  |
|                            |  |                                      |            |   |  |

Figure 26 L2S-M resources successfully installed in both clusters

After this installation, the mNCC can interconnect NEMO workloads in these managed K8s clusters, which showcases how the new L2SM-MD component can greatly assist the procedure of setting up the inter-cluster communication between K8s clusters belonging to a NEMO infrastructure.

#### 6.3.2 Intent-Based System

In order to showcase the advancements in the Intent-Based System, two different cases will be described. The purpose of the first one will be to describe the full intent lifecycle that the IBS follows to translate an Intent to the specific network technology. In this case it will be using the TFS adaptor. The second one, will show the integration with the L2SM component and making use of the cloud continuum intents for intercluster connectivity.

#### 6.3.2.1 Intent lifecycle. TFS L2VPN adaptor.

As explained in previous sections and deliverables (4.2.1, [1]), the Intent lifecycle is divided mainly in classification, translation and execution. The next logs snippets are part of an execution of the IBS managing the request of a new L2VPN creation in the intent format.

At the very beginning, the IBS detects all the intent libraries installed and loads all of them to later be able to translate to the different underlying technologies. This phase is divided in two parts: the one importing libraries Figure 27, and the one importing the executioners Figure 28.

![](_page_45_Picture_107.jpeg)

Figure 27 IBS importing libraries

![](_page_45_Picture_108.jpeg)

![](_page_46_Picture_0.jpeg)

![](_page_46_Picture_101.jpeg)

#### Figure 28 IBS importing executioners

All the executioners depicted in the previous figure are later available for the different libraries in case they are required. There is a specific executioner created for debugging purposes called "sys\_out", used to show the output of the intent translation. Any of them can be used at the same time, so at the end, the one handling TFS and the one handling the system out print will be activated. The fact that this is possible is showcasing also the flexibility of the architecture and the easy integration with different executioners and libraries depending on the needs of the user.

The next screenshot shows the intent incoming and having a first format check. In Figure 29, an arrow is showing the objectType of the intent, in this case "L2VPN". It is important to remark this because the intent will be understood as a layer two VPN but not yet as a TFS L2VPN.

![](_page_46_Picture_5.jpeg)

#### Figure 29 IBS input intent

In the Figure 30, it is showed how the comparison between the different libraries is traversed, and at the end, how the IBS is able to classify the intent as "L2VPN". This is due to the fact that, in the classification tree used, when the system reaches a leave, it means it fully matches all the keywords for the library.

![](_page_46_Picture_102.jpeg)

Figure 30 IBS first classification

![](_page_46_Picture_103.jpeg)

![](_page_47_Picture_0.jpeg)

The shows the IBS passing the intent to the L2VPN library. As this library doesn't generate ILUs (Intent Logic Units), the library reclassifies the intent (now called sub-intent), into a less abstracted library the TFS controller one. This step is important to abstract less abstracted libraries from higher ones, this means that the TFS controller library has no need to be aware of more abstracted L2VPN request, and the L2VPN must be aware of the specific technology library but not of the full translation to the technology. The step of reclassifying the intent is done until a library capable of generating an ILU is executed.

![](_page_47_Picture_2.jpeg)

Figure 31: IBS subintent generation.

Also, in the reclassification step, the library can make adjustments to the intent so that the following library is able to detect the intent as own. As shown in Figure 31 the "*objectType*" of the intent has changed. Now the sub-intent is passed through the classification again and detected as "*tfs\_controller*" intent.

![](_page_47_Picture_113.jpeg)

Figure 32 IBS second classification

In the Figure 32, it is also shown how now the intent is classified as ILU. From this point, it starts the translation phase. In the Figure 33, it is shown the parsing of the intent, and how it traverses all the contexts, targets and expectations.

![](_page_47_Picture_114.jpeg)

![](_page_48_Picture_0.jpeg)

![](_page_48_Picture_82.jpeg)

#### Figure 33 IBS tfs 12vpn translation

Finally, when the intent is translated, the library in charge of the translation calls the executioners needed to execute the intent. As explained earlier this case shows a first one calling "*sys\_out*" () and a second one to the real "*tfs\_connector*" ().

![](_page_48_Figure_4.jpeg)

![](_page_48_Picture_83.jpeg)

![](_page_49_Picture_0.jpeg)

X

Now, the executioner starts the proper protocol to create a connection to TFS north bound interface and makes a request for a new L2VPN connection.

![](_page_49_Picture_82.jpeg)

#### Figure 36 IBS http request to TFS

As a result of the process, a VPN service in TFS controller is created. In Figure 37, notice how the service is active on the nodes requested, and in Figure 38, are shown all the details translated from the *intentContext* and the *intentTargets* specified in the input intent.

![](_page_49_Picture_83.jpeg)

3.3.3.3 @ / 0/0/1-GigabitEthernet0/0/0/1 5.5.5.5 @ / 0/0/1-GigabitEthernet0/0/0/1

#### Figure 38 TFS webui L2VPN service details

![](_page_49_Picture_84.jpeg)

![](_page_50_Picture_0.jpeg)

#### 6.3.2.2 Cloud continuum Intent. L2SM MD connectivity

This section will show how an L2SM network is deployed through an intent coming to the IBS (full intent on annex 9.2). In the Figure 39, it is shown how the classification step detects the L2SM intent and calls the L2SM library.

![](_page_50_Picture_106.jpeg)

![](_page_50_Figure_4.jpeg)

From this point, the L2SM library is in charge of translating the intent to the corresponding interface that L2SM expects. The translation is depicted in next Figure 40.

![](_page_50_Picture_6.jpeg)

Figure 40: Final L2SM translation.

Finally, once the translated intent is executed in L2SM, it creates a new Kubernetes intercluster network as shown in Figure 41, where a Kubernetes command is executed to verify that everything works as expected.

![](_page_50_Picture_107.jpeg)

![](_page_51_Picture_0.jpeg)

ntent-based-system\$ kubectl get l2networks --context kind-worker-cluster-1 AVAILABILITY **CONNECTED PODS NAMESPACE NAME** AGE Available spain-network  $default$  $2m18s$ 

#### Figure 41: L2SM intercluster network active.

#### 6.3.3 Multi-Cluster monitoring and exposure

In order to perform the PoC of the multi-cluster monitoring and exposure, the mNCC components in charge of monitoring and exposure of the mNCC have been deployed in a scenario with 3 nodes. The mNCC monitoring and exposure process is explained in section 4, so we will not extend with this explanation, but it is worth remembering that the monitoring is based on the communication between pods deployed in each node and then shared with the exposure module through a local Prometheus. Once the exposure module has those metrics, it formats them and indicates to which cluster they belong and at what time they have been generated.

For these tests, we have reduced the monitoring and exposure time to 2 minutes (120 seconds) to show how the RabbitMQ queue is being updated, although in the joint environment these measurements would be hourly (3600s) to avoid saturation in the network and in the metrics queues.

In the process of evaluating the mNCC metrics exposure we must start with the deployment of the probes and the exposure module (Nemex for short) in each cluster, counting on a pod of probes per worker node and a Nemex per cluster. For this proof of concept, we will perform the evaluation on 2 clusters in parallel.

In Figure 42 and Figure 43 we can see a test run of the monitoring pods in which the logs of one of the probes of each cluster are obtained. These logs show the measurements taken periodically and shared with the Nemex through an internal Prometheus (Figure 44 shows the format of these logs).

| ubuntu@alto-server:~\$ kubectl logs -n nemo-net network-probe-daemonset-5grrd  |
|--|
| * Serving Flask app 'network probe'  |
| $\star$ Debug mode: off  |
| $2024 - 12 - 12$ 16:18:20,420 INFO - Pushing metrics to Prometheus on port 5001.                                     |
| 2024-12-12 16:18:20,469 / INFO   |
| 2024-12-12 16:18:20,470 - INFO - Performing network measurements   |
| 2024-12-12 16:18:20, 470 - INFO - Target host: 172.18.0.2  |
| 2024-12-12 16:18:20,470 - INFO - Target port: 80   |
| 2024-12-12 $16:18:20,470$ - INFO - -----------   |
| 2024-12-12 16:18:22, 472 - INFO - Measured Throughput: 12809.54 Mbps   |
| 2024-12-12 16:18:22.472 - INFO - Measured Energy: 1691.07 W  |
| 2024-12-12 16:18:22,472 - INFO - Time taken for Throughput measurement: 2.0016 seconds                               |
| $2024 - 12 - 12$ $16:18:22,472$ - INFO - --  |
| 2024-12-12 16:18:24.510 - INFO - Measured Packet Loss Rate: 0.00%  |
| 2024-12-12 16:18:24,510 - INFO - Time taken for Packet Loss measurement: 2.0378 seconds                              |
| $2024 - 12 - 12$ 16:18:24,510 - INFO - -   |
| 2024-12-12 16:18:24,511 - INFO - Measured Latency: 0.28 ms   |
| 2024-12-12 16:18:24,511 - INFO - Time taken for Latency measurement: 0.0004 seconds                                  |
| 2024-12-12 16:18:24.511 - INFO - -   |
| 2024-12-12 16:18:24,511 - INFO - Total time taken for all measurements: 4.0412 seconds                               |
| 2024-12-12 16:18:24,511 - INFO - --------------------  |
| $2024 - 12 - 12$ 16:18:27.512 - INFO - -------   |
| 2024-12-12 16:18:27,513 - INFO - Performing network measurements   |
| 2024-12-12 16:18:27,513 - INFO - Target host: 172.18.0.4   |
| 2024-12-12 16:18:27.513 - INFO - Target port: 80   |
| 2024-12-12 16:18:27,513 - INFO - -   |
| 2024-12-12 16:18:29,514 - INFO - Measured Throughput: 13290.12 Mbps  |
| 2024-12-12 16:18:29,514 - INFO - Measured Energy: 1754.17 W  |
| 2024-12-12 16:18:29,514 - INFO - Time taken for Throughput measurement: 2.0010 seconds                               |
| 2024-12-12 16:18:29,515 - INFO -   |
| 2024-12-12 16:18:31,569 - INFO - Measured Packet Loss Rate: 0.00%  |
| 2024-12-12 16:18:31,569 - INFO - Time taken for Packet Loss measurement: 2.0538 seconds<br>3034 13 16:10:31 ECO TNEO |
|  |

Figure 42 Logs from the network probes in the first cluster.

![](_page_51_Picture_132.jpeg)

![](_page_52_Picture_0.jpeg)

![](_page_52_Picture_69.jpeg)

Figure 43 Logs from the network probes in the second cluster.

![](_page_52_Figure_3.jpeg)

Figure 44 Metrics saved in the internal Prometheus in the first cluster.

![](_page_52_Picture_70.jpeg)

![](_page_53_Picture_0.jpeg)

In order to show this last capture, we have performed a port-forwarding to the host system, since this service is only exposed within the nemo-net network, so that other systems or users cannot access them autonomously.

In parallel, the Nemex component performs periodic queries to this Prometheus, and integrates the metrics together with the information of the cluster and the time when the exposure is performed. In this way, the components that require this information will be able to access it.

In Figure 45 we can see how from RabbitMQ we can see the pushes to the mncc\_cmv queue (mNCC Cost Map Vectorial), where at the beginning we have a series of short peaks and after a while more elongated peaks appear. This is due to the fact that, at the beginning, only one cluster was launched, but when testing with several clusters, they started to send the metrics slightly out of sync. Also, in the upper part of the figure, the logs are shown from the two Nemex pods. Reading the first lines it is possible to check that the upper-left window shows the "kind-kind" cluster and the upper-right the "kind-kind-2" cluster. These clusters were launched in two different devices in the same lab, in order to check the correct behavior of the multi-cluster monitoring and exposure functionality.

![](_page_53_Figure_4.jpeg)

updates.

These metrics in turn are accessible by the Meta Orchestrator and CF-DRL components to make decisions having knowledge of the state of the monitored network.

![](_page_53_Picture_111.jpeg)

![](_page_54_Picture_0.jpeg)

 $\overrightarrow{O}$ 

# 7 Conclusions

This document reports the final outcomes of the components developed in Work Package 2, namely the CMDT, the CF-DRL and the mNCC. It also includes details on the TSN capabilities integrated on the NEMO edge-cloud continuum for satisfying specific use cases requiring time-sensitive behavior.

This deliverable summarizes the progress of the developments, the integration aspects with respect other components of the NEMO stack, as well as provides exemplary details of the functional behavior of the components.<br>Final integration efforts will be reported in deliverables from other work packages when required. components.

Final integration efforts will be reported in deliverables from other work packages when required.

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![](_page_54_Picture_71.jpeg)

![](_page_55_Picture_0.jpeg)

# 8 References

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![](_page_55_Picture_122.jpeg)

![](_page_56_Picture_0.jpeg)

# 9 Annexes

# 9.1 TFS interface and example intent

![](_page_56_Picture_171.jpeg)

![](_page_56_Picture_172.jpeg)

![](_page_57_Picture_0.jpeg)

![](_page_57_Picture_196.jpeg)

![](_page_57_Picture_197.jpeg)

![](_page_58_Picture_0.jpeg)

# 9.2 L2SM example intent

![](_page_58_Picture_214.jpeg)

![](_page_58_Picture_215.jpeg)

![](_page_59_Picture_0.jpeg)

intentPriority: 1 observationPeriod: 60 intentAdminState: 'ACTIVATED'

![](_page_59_Picture_43.jpeg)

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